

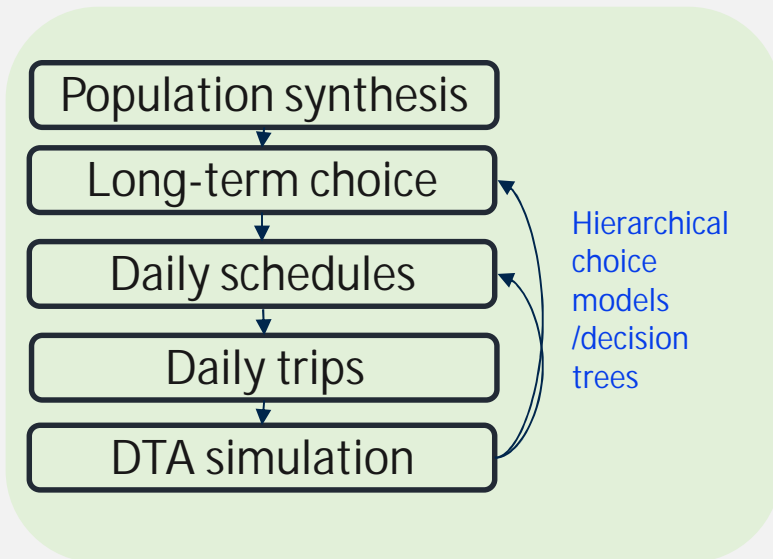
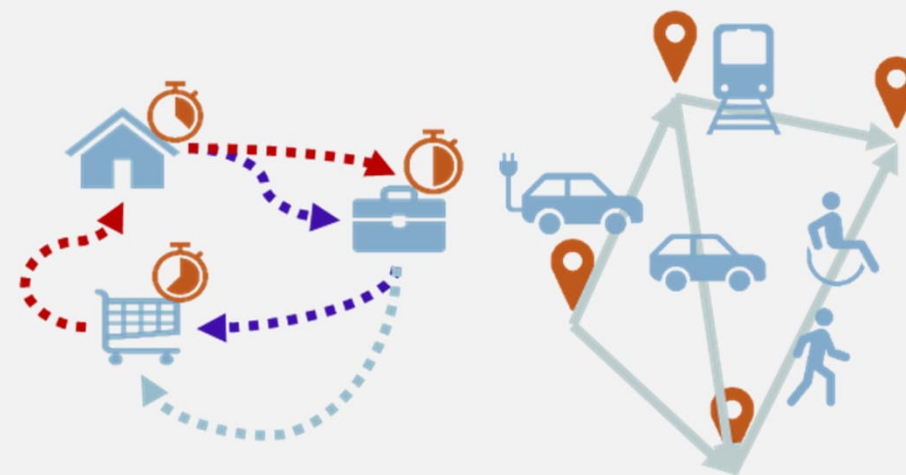
# Integrating Activity-Based Transportation Models with Large Language Model Agents

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# Activity-based Modeling

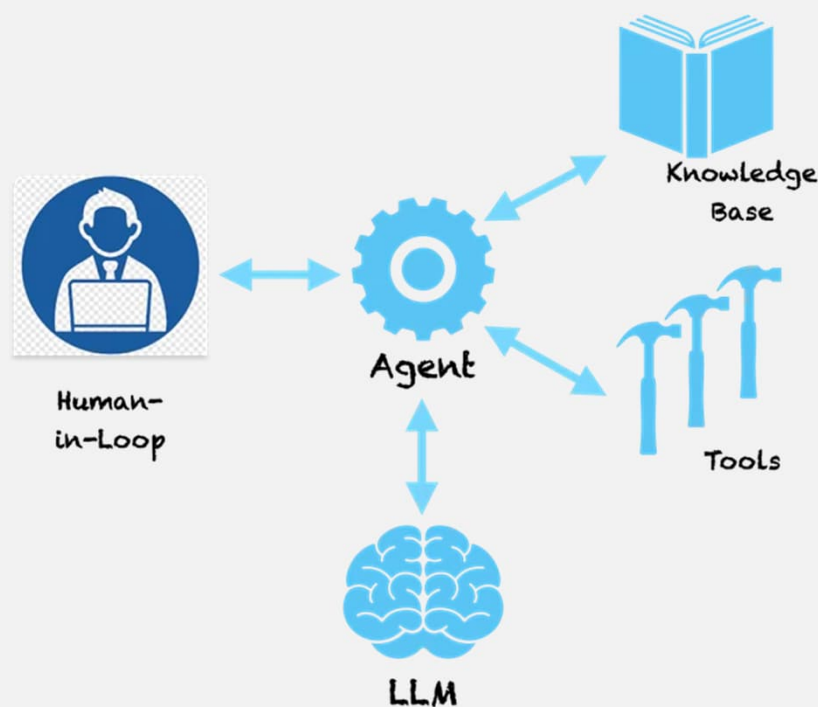
- ★ The-state-of-the-art paradigm of travel demand modeling
- ★ Recent efforts primarily leverage agent-based simulation



*Agents follow hardcoded condition-action rules to schedule daily activities and make travel plans. They can learn, adapt, and improve their interactions with other agents as well as their dynamic environment.*

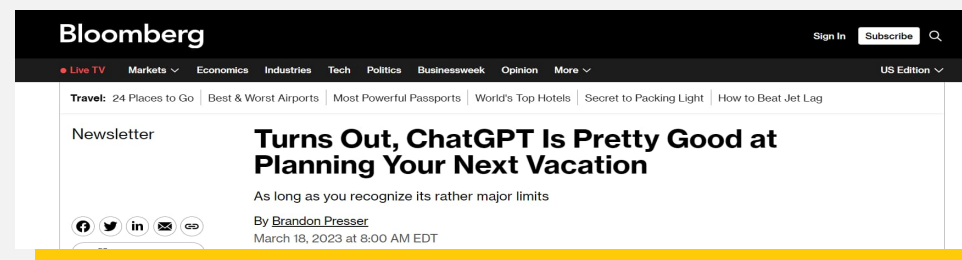
# LLM Agents

LLM-based or powered agent is a system that can use an LLM as “brain” to reason through a problem, create a plan to solve the problem, and execute the plan with the help of a set of tools

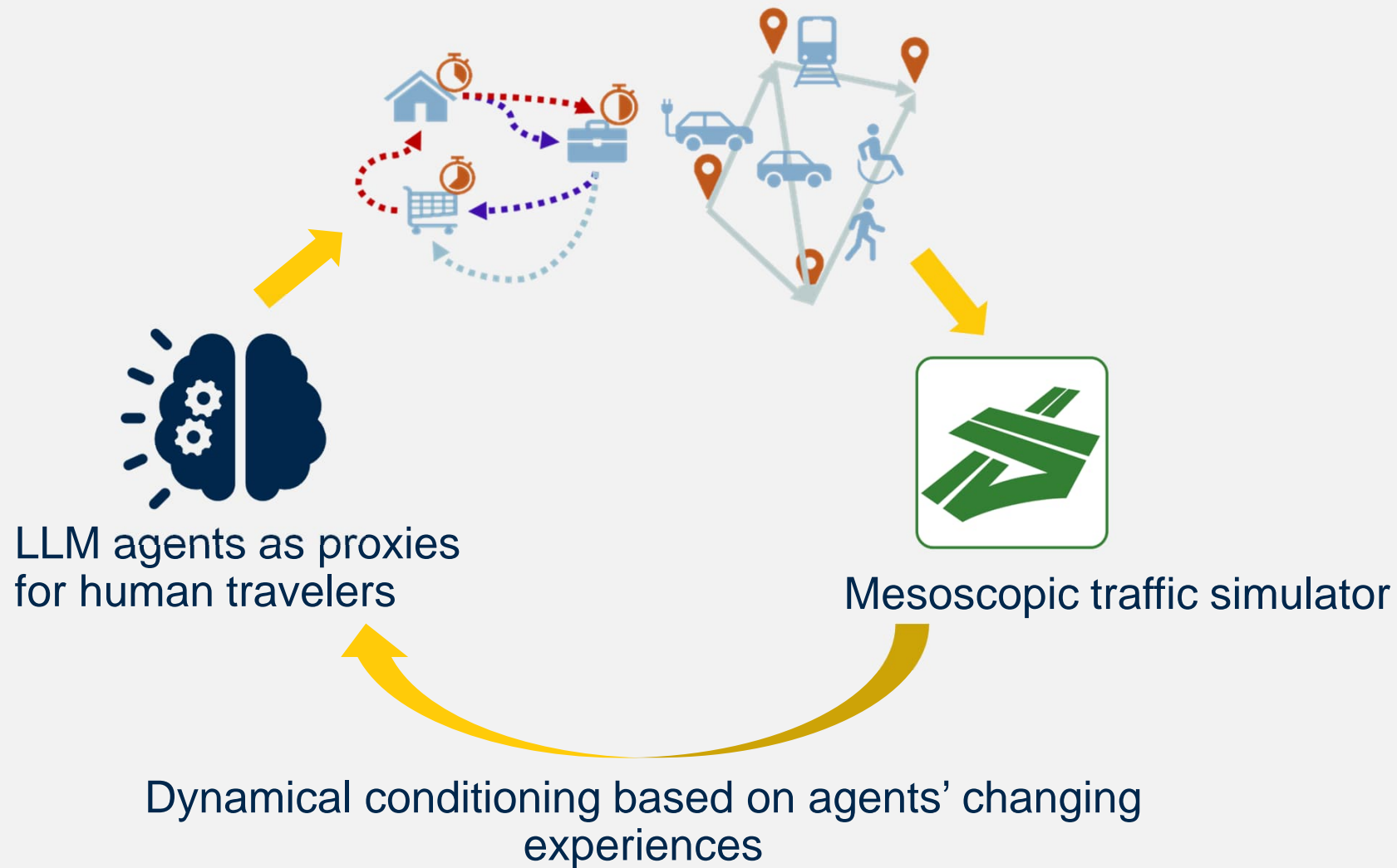


## ChatGPT

Powered by GPT-4, ChatGPT is a text-based, tool-augmented LLM agent that can assist with reasoning, planning, and problem-solving across various domains.



# LLM-Agent-Based Simulation for ABM





# LLM as a Proxy of Human Behavior

- Key hypothesis: LLMs have the potential to act as “silicon samples”
- Main reason is that LLM has three key properties:

Imitation in learning



Human-like Interaction



Instruction-following and role-play



Critical questions: how much do they align with human travel behavior?

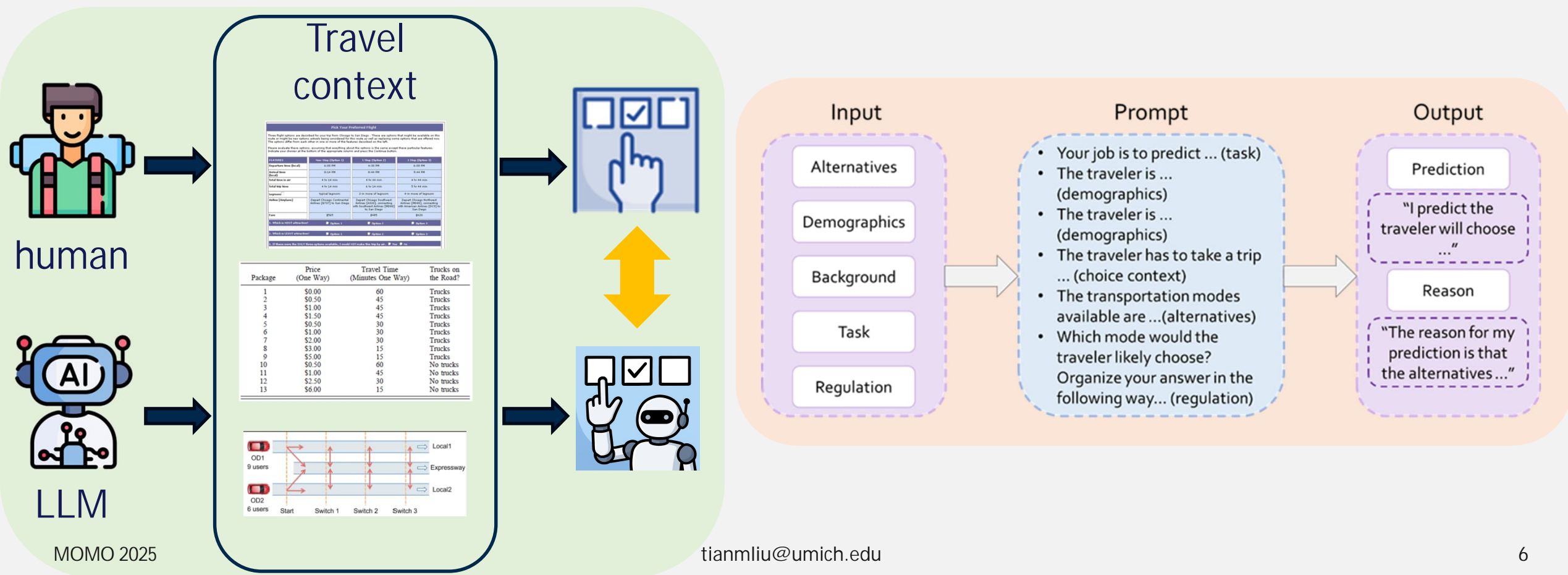
\* Grossmann, et al., AI and the transformation of social science research, Science, 2023, 380 (6650).

\*\* Hutson, M., Can AI chatbots replace human subjects in behavioral experiments. Science, 2023, 381(6654).

# How do we evaluate alignment?

We conduct evaluation on choice and learning levels

- Basic methodology: treat LLM as an autonomous traveler, prompt them with the same information, compare LLM&human responses



# LLM's VOTT

## Following Calfee et al. (2001)\*

- 13 options (packages) with varied travel time and cost
- Respondents are asked to provide ratings and a ranking of options
- Rankings are used to calibrate an ordered logit model

## Experiment

- Full factorial design experiment to control social-demographics and travel situation
- On each run we repeat survey 60 times on GPT 4o with temperature 1.

*\*J. Calfee, C. Winston, R. Stempiski (2001) Econometric issues in estimating consumer preferences from stated preference data: a case study of the value of automobile travel time, Review of Economics and Statistics, 83, pp. 699-707*

Package	Price (One Way)	Travel Time (Minutes One Way)	Trucks on the Road?
1	\$0.00	60	Trucks
2	\$0.50	45	Trucks
3	\$1.00	45	Trucks
4	\$1.50	45	Trucks
5	\$0.50	30	Trucks
6	\$1.00	30	Trucks
7	\$2.00	30	Trucks
8	\$3.00	15	Trucks
9	\$5.00	15	Trucks
10	\$0.50	60	No trucks
11	\$1.00	45	No trucks
12	\$2.50	30	No trucks
13	\$6.00	15	No trucks

Factors	Levels			
Purpose	Leisure	Personal	Commute	Business
Age	25-29		55-59	
Sex	Male		Female	
Education	High-school		College	
Wage	\$15/hour	\$25/hour	\$35/hour	\$50/hour

# LLM's VOTT

Factor	Level	GPT-4o	Factor	Level	GPT-4o
Purpose	Leisure	\$7.12/h	Wage per hour	\$15	\$6.47/h
	Commute	\$8.54/h		\$25	\$7.80/h
	Business	\$8.22/h		\$35	\$8.38/h
	Personal	\$7.88/h		\$50	\$8.77/h

Income Elasticity				
Purpose	USDOT	Binsuwadan et al. (2023)*	Shires and de Jong (2009)**	GPT-4o
Commute	1	0.37	0.67	0.24
Business	1	0.53	0.47	0.21
Leisure	1	0.53	0.52	0.22
Personal	1	0.53	0.52	0.22

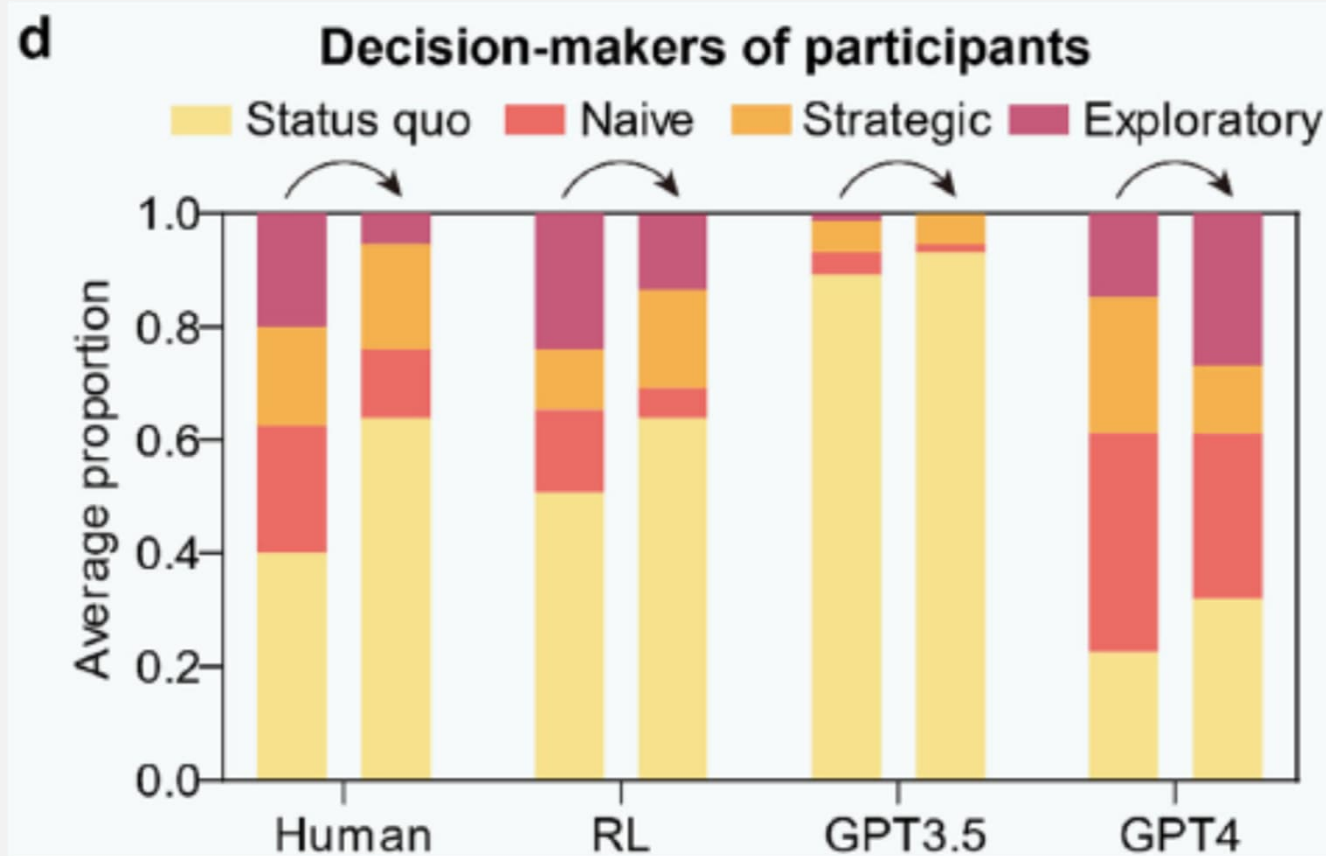
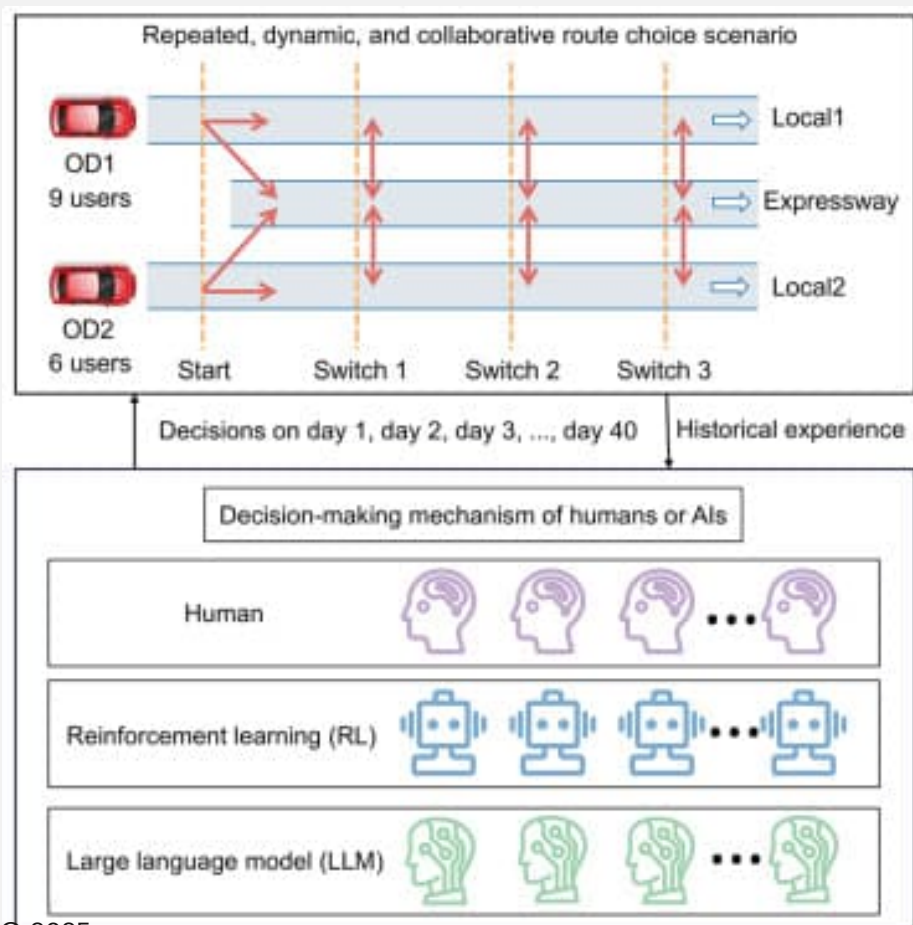
\*Binsuwadan, J., Wardman, M., de Jong, G., Batley, R., and Wheat, P. (2023). The income elasticity of the value of travel time savings: A meta-analysis, Transport Policy, Volume 136, 126-136.

\*\*Shires, J. D., & de Jong, G. C. (2009). An international meta-analysis of values of travel time savings. Evaluation and program planning, 32(4), 315-325.



# LLM's learning and choice adaptation

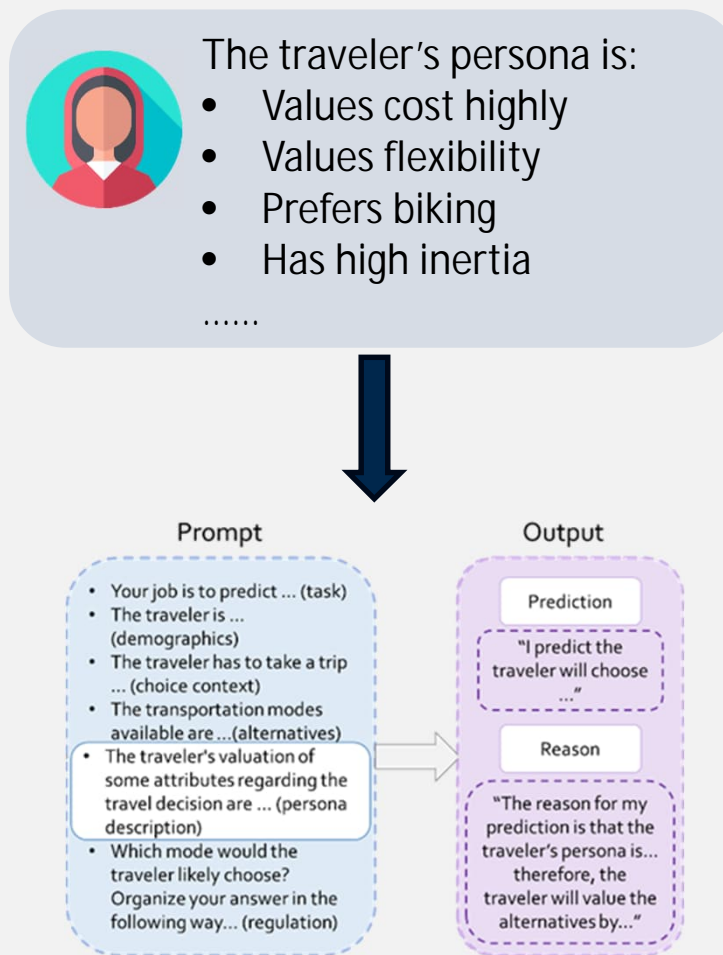
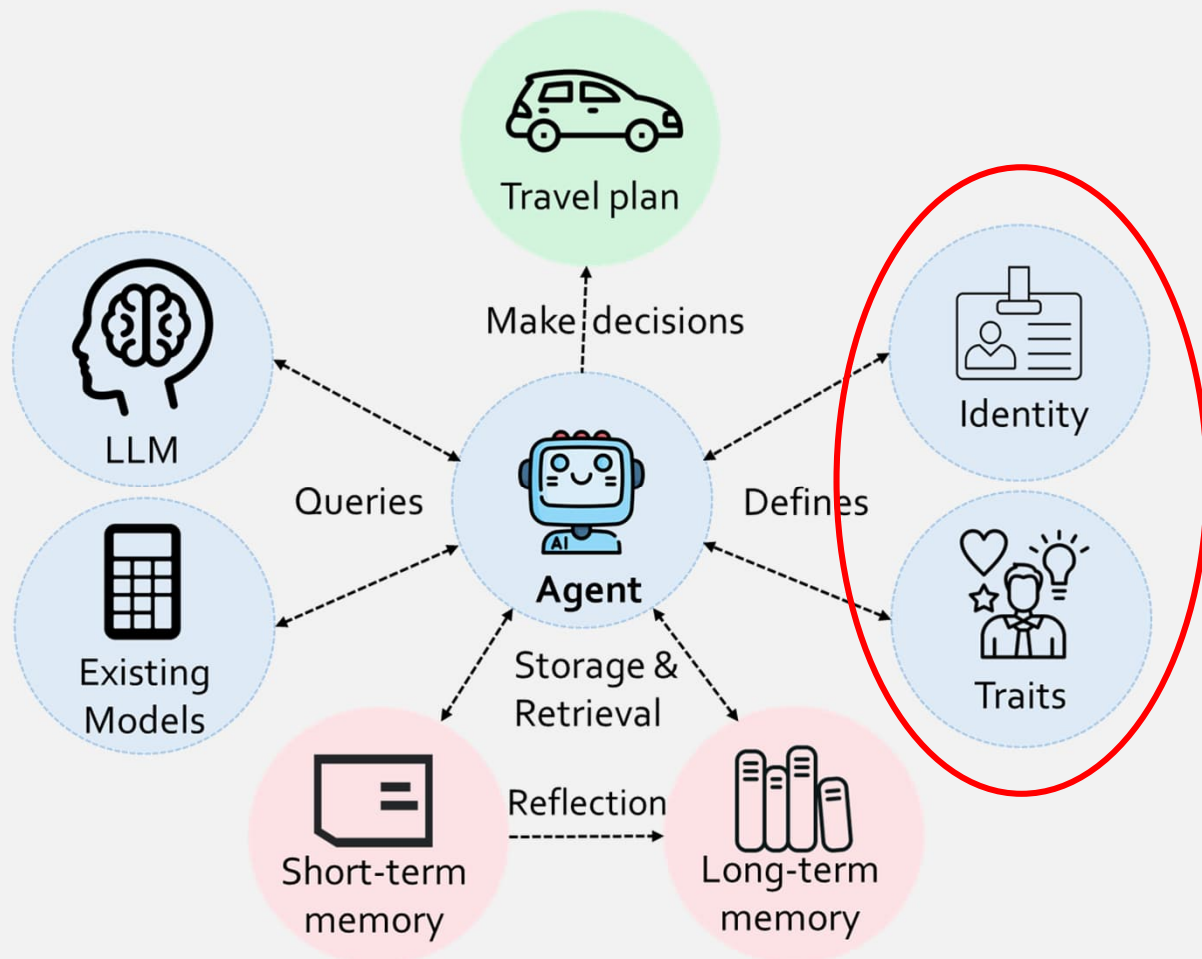
- LLMs and humans are put into the same commuting route choice experiment
- LLMs exhibit significantly different adaptation behaviors than humans.



# Humanize LLMs

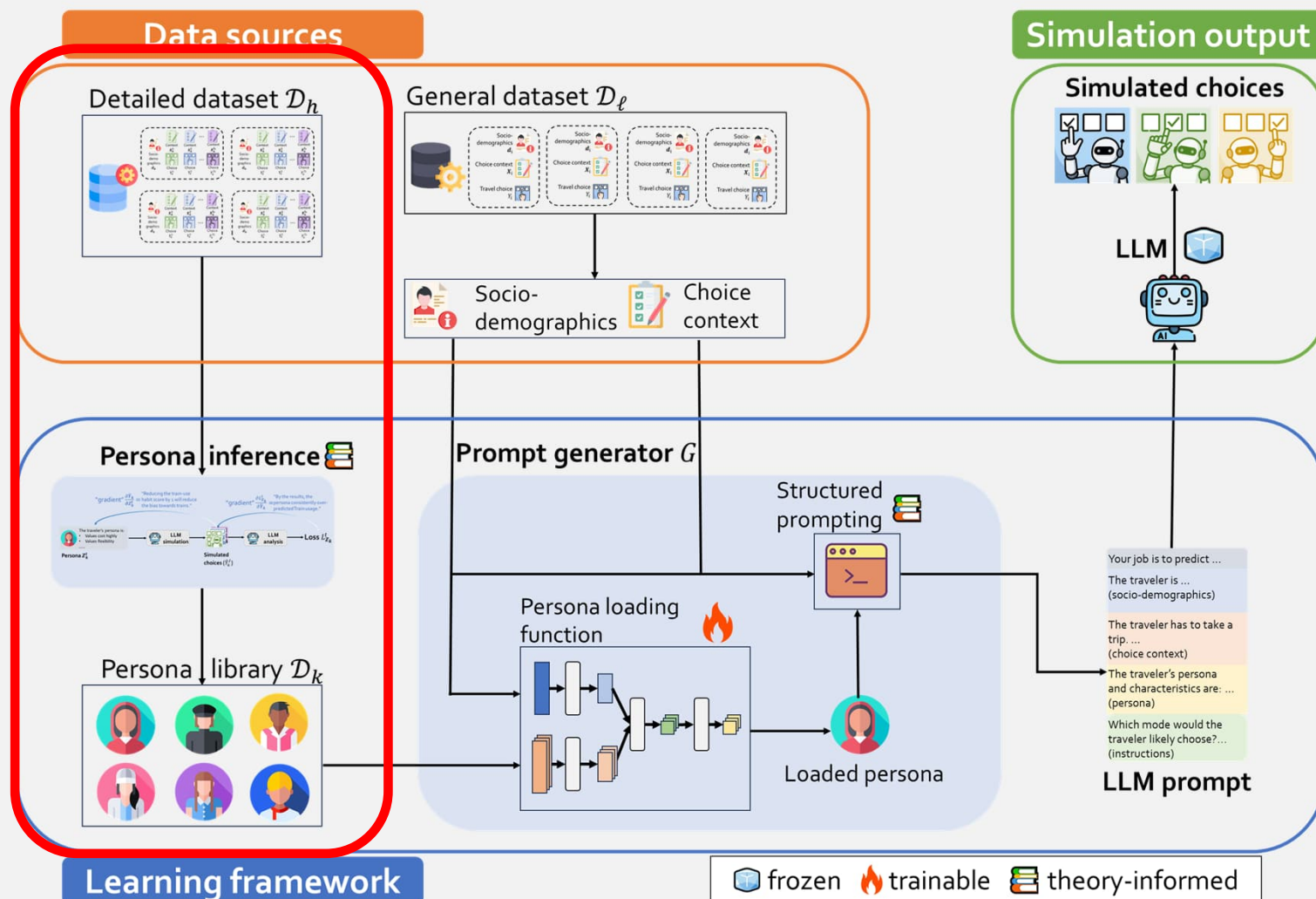
Our key idea: persona

- Textual representation capturing the preferences and traits of the person



# Alignment: choice modeling

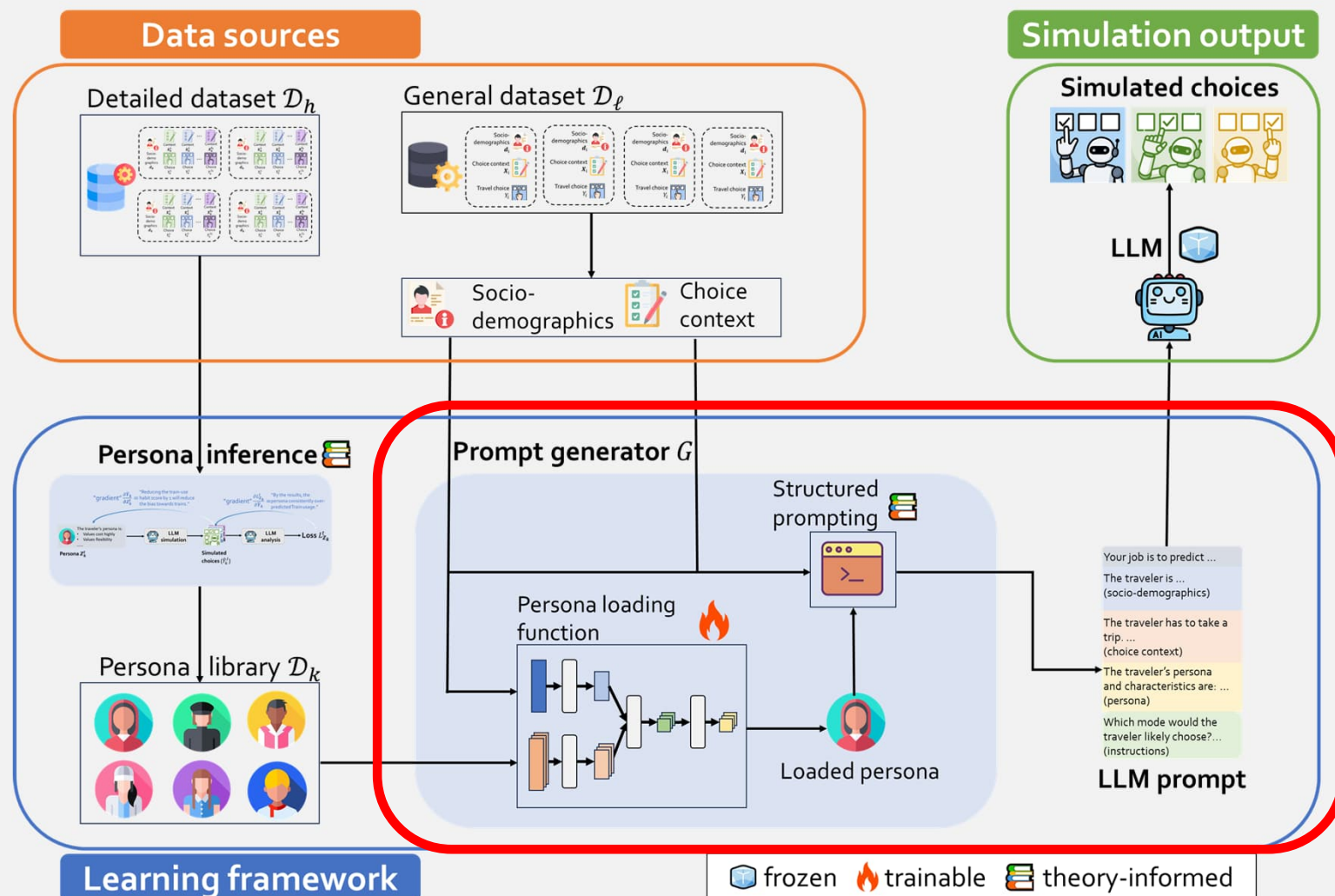
Our main approach involves two key steps:



Step 1:  
Define and inversely learn a  
set of LLM persona from  
data

# Alignment: choice modeling

Our main approach involves two key steps:



Step 1:  
Define and inversely learn a  
set of LLM persona from  
data

Step 2:  
Learn a persona loading  
function based using latent  
embeddings and underlying  
behavior similarities



# Choice model: results

Method	Train	Mode Split Swissmetro	Car	JSD (in 0.1 bits)	Marco F1	Weighted F1
Ground truth	6.0%	54.0%	40.0%	0.000	1.000	1.000
MNL	1.5%	79.0%	19.5%	0.548	0.464	0.617
Zero-shot LLM	13.5%	73.5%	13.0%	0.735	0.438	0.542
Few-shot LLM	13.0%	59.5%	27.5%	0.188	0.446	0.579
Liu et al. 2024	5.5%	62.5%	32.0%	0.055	0.493	0.648
Our method	4.5%	60.0%	35.5%	0.029	0.541	0.691

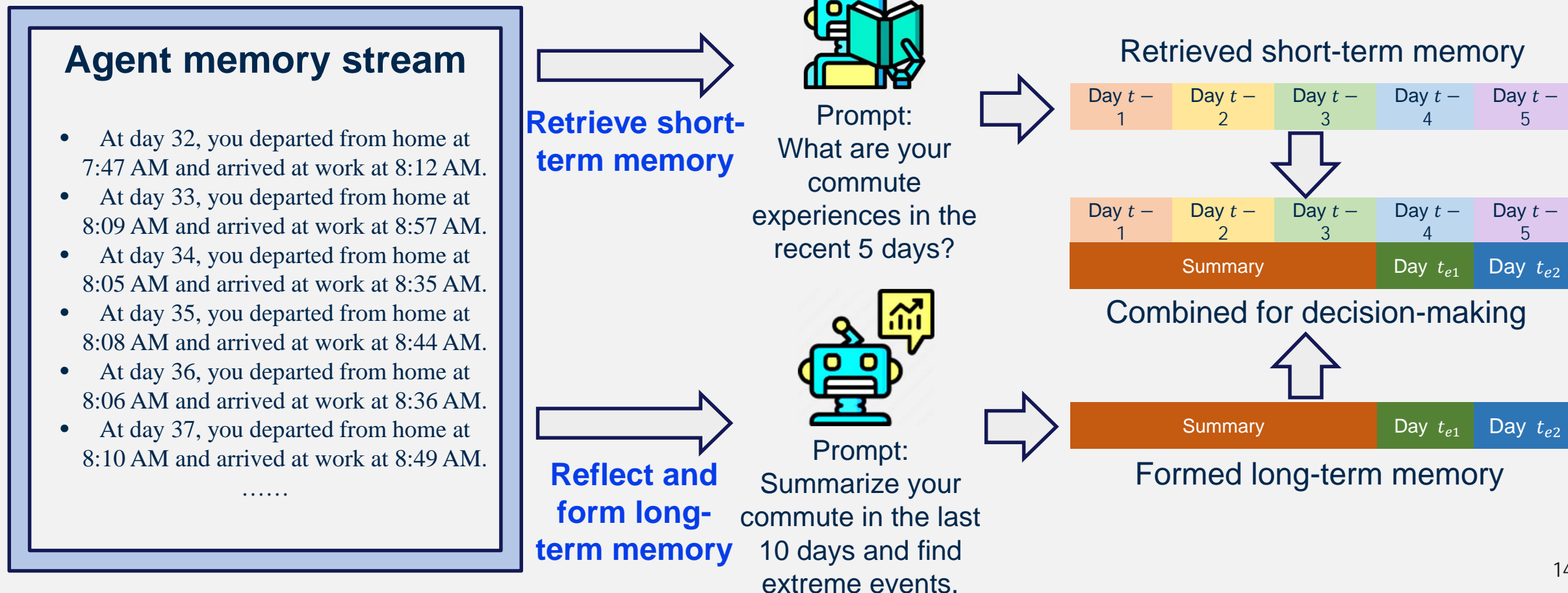
Experiment: Swissmetro mode choice dataset+GPT-4o

Takeaways: our method exceeds existing methods' performances in

- Generating a more realistic aggregate alternative share prediction
- Producing more accurate individual behavior prediction

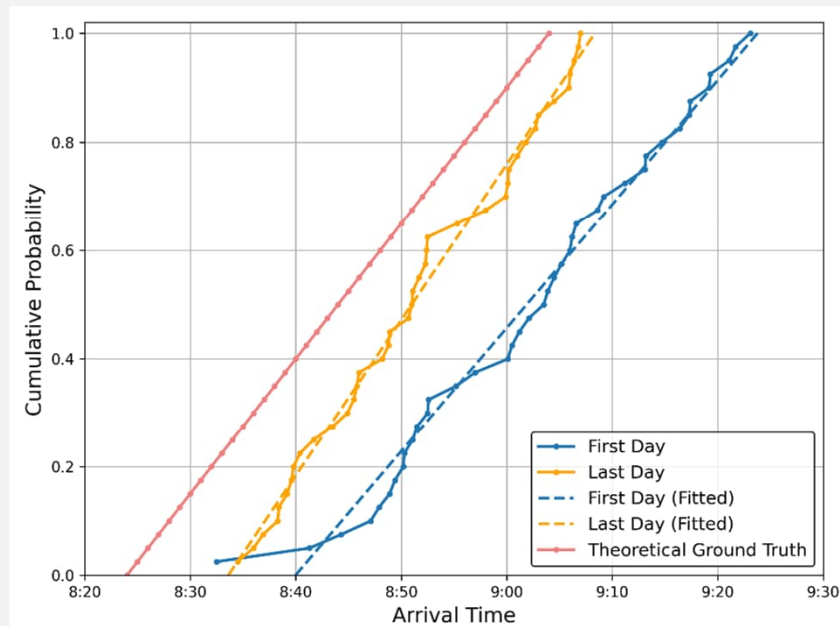
# Alignment: day-to-day adaptation

- LLM agents use a combination of short-term memories and long-term memories when making their decisions.
- Other adjustments: adding human traits (e.g. inertia) in persona

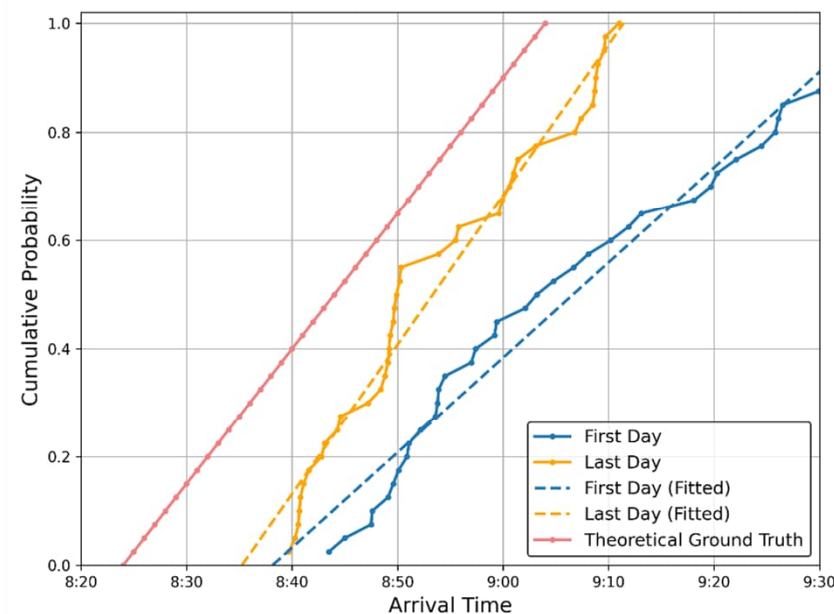


# Day-to-day adaptation: results

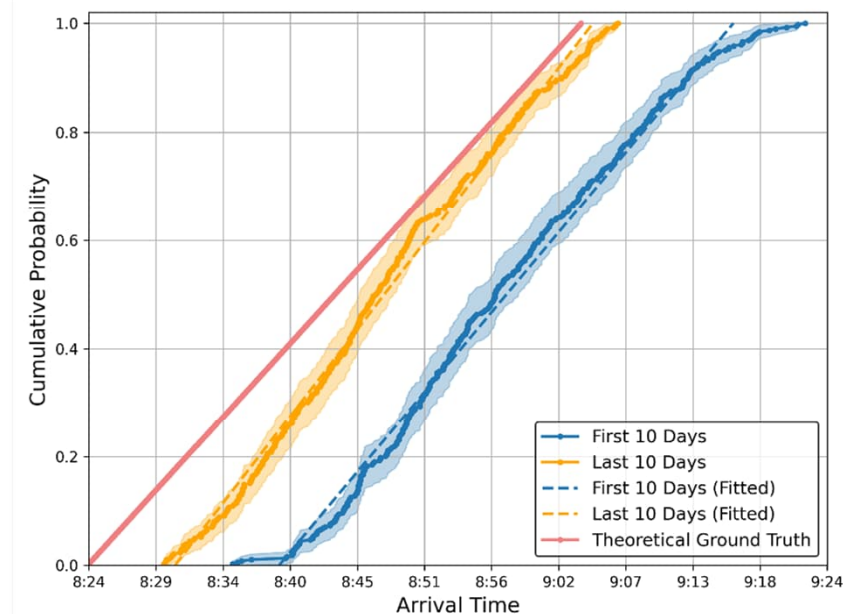
- We put our approach into a day-to-day departure choice context and compare it with other agents.
- Our proposal facilitates better learning behavior and converge most closely to ground truth (red line).



Vanilla agents



CoT-only agents



Proposed agents

# Key challenges

## Behavioral Alignment

- ★ LLMs struggle to replicate natural randomness in human behavior
- ★ Risk of systematic biases due to skewed training data
- ★ Lack of integration of attitudinal variables (e.g., preferences, values)
- ★ Value alignment during training may distort behavioral realism

## Validation

- ★ Need for rigorous micro-level and macro-level validation
- ★ Individual-level misalignment can amplify into system-level errors

## Scalability

- ★ High computational cost for simulating large agent populations
- ★ Latency due to token-by-token LLM inference
- ★ Requires special techniques (e.g., batching, quantization) for large-scale deployment



# Takeaways

Our idea: using LLM to augment agent-based modeling

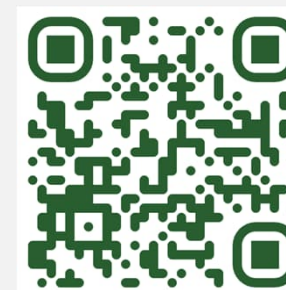
Takeaways:

- LLMs alone can imitate some human trends in travel demand, but has significant limitations
- Persona and memory system can significantly enhance LLM agent's ability to simulate human travel
- LLM agents have potential but also requires further development

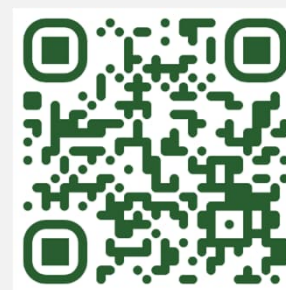
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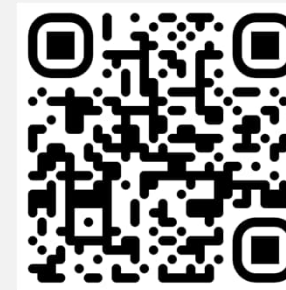
vision



Mode choice eval



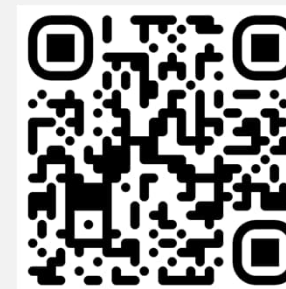
VOTT eval



choice alignment



learning eval



learning alignment



**limos** lab for innovative  
mobility systems

**Thank You!**

**tianmliu@umich.edu**

# Future opportunities

## Behavioral Alignment

- ★ More expansive and efficient distributional alignment method
- ★ Leverage multimodal and multi-source data
- ★ Identify the optimal mixture for hybrid modeling

## Validation

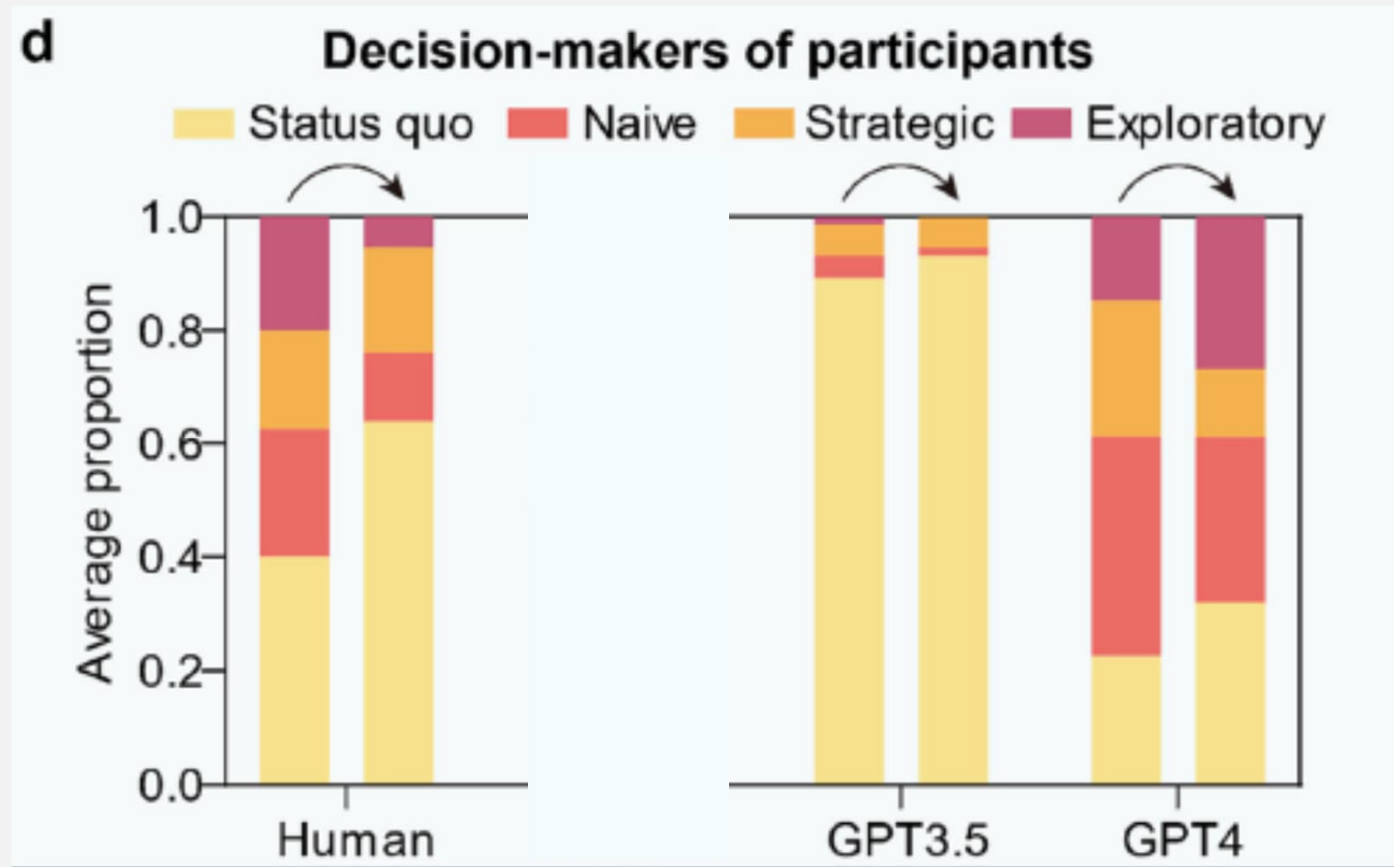
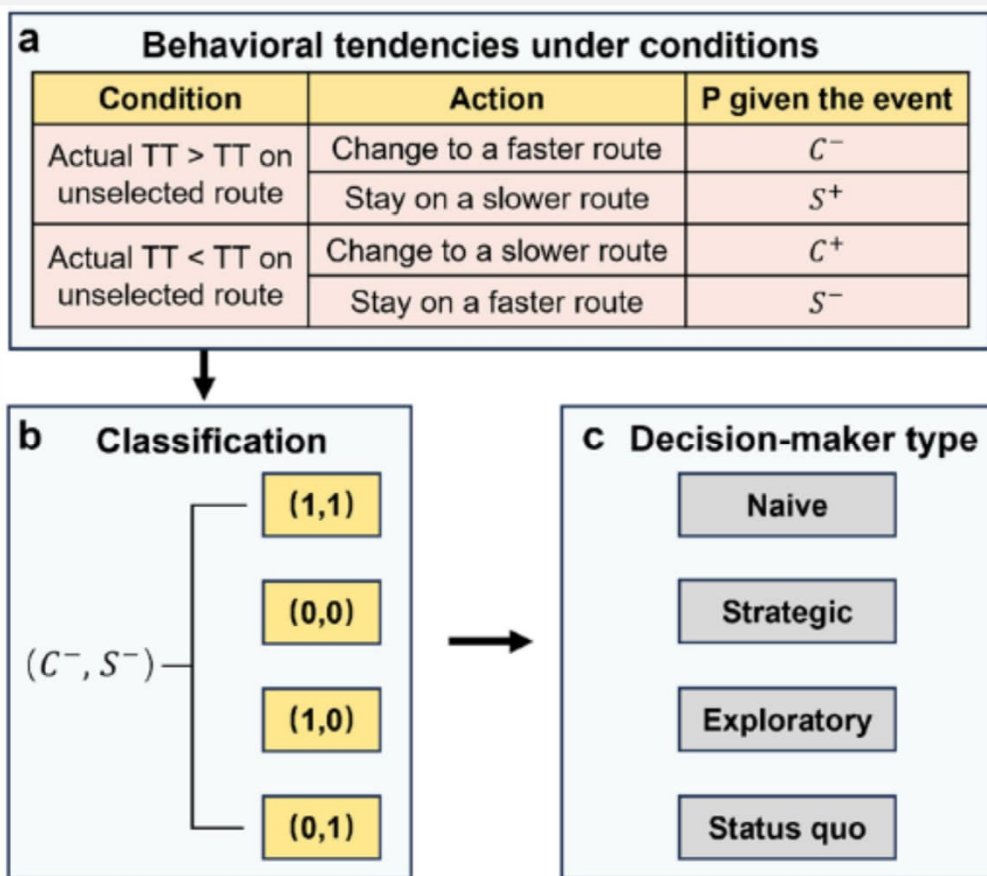
- ★ Expansive testing of LLM behavior
- ★ More evaluation and improvement of the value/need level

## Scalability

- ★ Computational optimization (e.g. parallel computing)
- ★ Application of small language models

# LLM's learning and choice adaptation

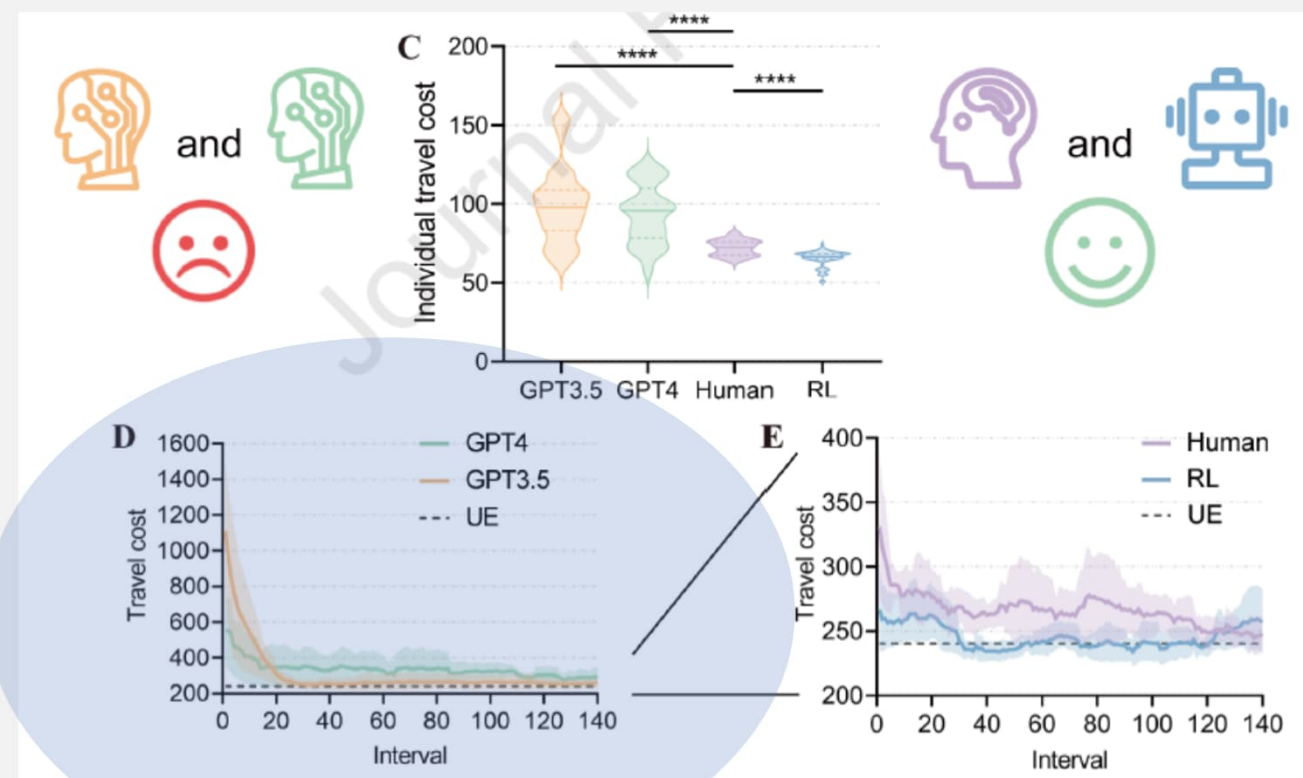
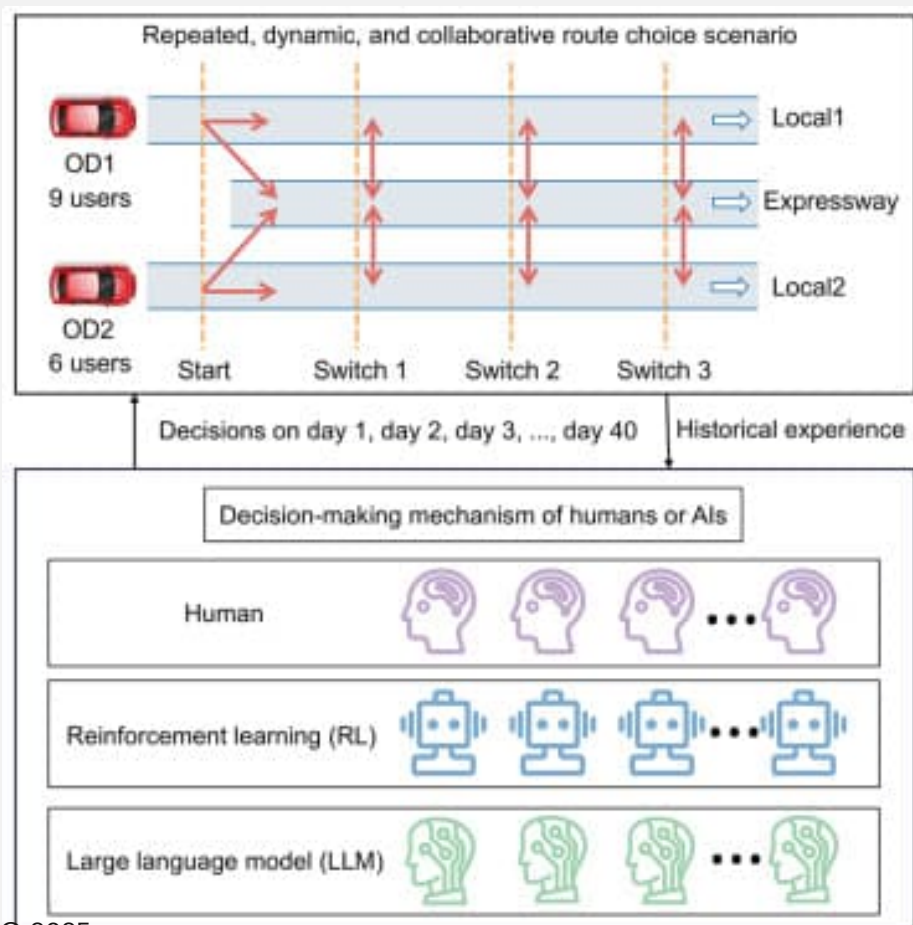
LLMs exhibit significantly different adaptation behaviors than humans.





# LLM's learning and choice adaptation

- LLMs and humans are put into the same commuting route choice experiment
- The resulting system dynamics is also vastly different



# Alignment: day-to-day adaptation

We design the agents for them to have human-like decision making traits and memories:

- Key: enhancing persona with clear values and human decision-making traits

